

PROTECTION OF SUBSEA INFRASTRUCTURE
IN ICE ENVIRONMENTS

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by

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This thesis begins with an outlook of the offshore Newfoundland oil and gas industry. While hydrocarbon resources are plentiful, adverse operating conditions and risk of impact from encroaching icebergs leads to challenges in design, project execution and operation. Acceptable risk levels regarding hydrocarbon release to the environment have to be met by providing sufficient protection for vulnerable assets. A discussion on the parameters involved in determining contact risk between the keel of an iceberg and a

For subsea structures, many protection concepts have been considered for application in selected concept for major field development and production schemes on the Grand that only require limited subsea infrastructure. Other protection concepts which have

The Protection of subsea installations required for subsea tie-back developments via tubular frame protection structures is proposed in the present study. Three different geometric configurations are analyzed. The first configuration consists of a rectangular structure has a large circular base and a smaller circular top portion, with the top and base connected using straight inclined members, to give the appearance of a truncated conical

structural response of the frames subjected to ice loading. Primary failure mechanisms during ice-subsea structure interaction are assessed using an energy approach. Design loads are estimated using a simple ice load model accounting for crushing failure of the

Progress in this research area should involve simulation of a wider range of ice contact events. It is suggested that the finite element model be improved toward continuum

substructure modeled using kinematic constraints representing iceberg size and stability

guidance and I met during the completion of this project in its entirety. I would also like to express gratitude to Paul Sluckey, Freeman Ralph, and Tony King of C-CORE for

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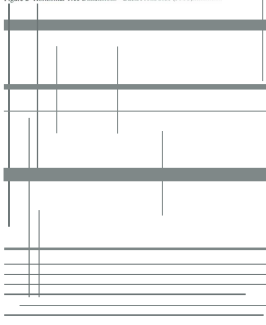
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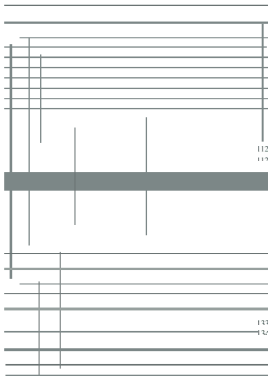


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LIST OF SYMBOLS

C_{NET}	Net incremental system cost
C_{CAPEX}	Incremental capex cost
C_{RISK}	Cost of risk from icebergs
	Equipment repair/replacement cost
	Environmental and equipment cleanup cost
	Height of subsea facility above seabed
	Iceberg draft
	Waterline length of iceberg
	Annual contact frequency between scouring icebergs and subsea facilities
	Proportion of icebergs with draft capable of contacting subsea facility
\overline{W}_B	Mean width of free-floating keels
D_f	Effective diameter of subsea facility

Normal force at iceberg keel
Horizontal force at iceberg keel
Vertical force at iceberg keel
Slope angle of structure face

M_{righting}

Righting moment of iceberg

\overline{KG}

Distance from keel to center of gravity

 I_{sp}

Waterplane moment of inertia

 \bar{q}_u

Ultimate vertical bearing resistance of soil

expected to plateau within the next few years meaning new assets need to be exploited to maintain full production capacity. Marginal field development has acted as a catalyst

The present study begins by reviewing the current state of the offshore onshore and

production is declining. The issue at the core of this work is the potential for iceberg keel

Obstacle impacts or interference from trawl gear. In ice environments the goal is iceberg avoidance or iceberg resistance. For subsea facilities extending above the ocean no or

contact. The parameters involved in the calculation of risk with free-floating and

The goal of this study is to assess the potential of protecting single sack-late oil producing wells using a structural frame. To estimate global loads imposed during the ice keel-

energy to work done through crushing and pitch and heave motions. Based on the analysis, a simplification of the energy model is used. It is assumed conservatively that energy is dissipated in crushing failure of ice over the contact area only.

The loads determined from this approach are then applied to the prototype frame using

developed to simulate pile-soil interaction, soil-structure bearing interaction and global structure response upon application of mean global ice crushing pressures. Three different structural configurations are analyzed and the results are discussed in detail. Finally, conclusions of the present study are drawn and recommendations put forth for

sareguardorsinglesubseasatellitewell installationsagainstice keel contact. The intent is not to propose this idea as the best solution, rather to verify whether or not protection

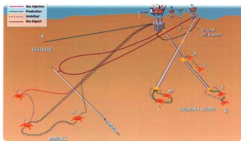
The desired result of the analysis is a nearly optimal protection structure. The first step is

space for ROV access and workover. There should also be sufficient clearance to allow

configuration will be made more nearly optimal through successive iterations. The analysis will begin with a simple rectangular frame, similar to conventional protection

framed cone with straight inclined members. The framed cone will then take more or a domed shape as the effectiveness of protection frame geometry (i.e. curved versus

Figure 1 depicts Europe's largest fixed-platform subsea back development fit the



production tree, typically called Christmas (Xmas) tree, and wellhead. The Xmas tree comprises valves, spools and fittings with a primary function to direct and control fluid

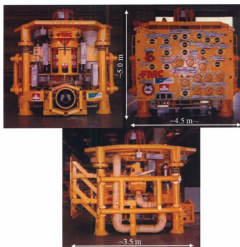
has a relatively low profile height versus the vertical tree leading to a reduction in contact

catastrophic failure modes. In the event of a direct iceberg impact with a tree, prevention

production tubing. Stresses induced in the production tubing, critical to reliable safety valve operation, will likely be higher for a horizontal tree cap than for a vertical tree cap.

potentially be realized with the implementation of sufficient impact protection

Figure 2 provides approximate dimensions for a typical horizontal tree used offshore

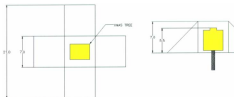


protection structures. Three structural configurations have been conceived based initially

analytical expressions that account for the system energy components and decoupling

failure mechanism
 modeled using
 by piles connected
 discrete nonlinear
 (2000) guide

The global structural response of a rectangular tubular frame structure (Figure 3) will be compared to that of a truncated cone structure (Figure 4) and then the potential benefit of introducing curved members will be examined. A ship protection structure takes a dome-like shape (Figure 5). The rectangular frame structure, including pile foundation, has an



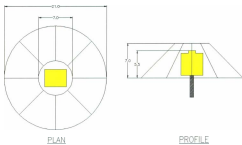
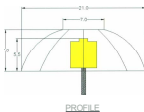


Figure4-Truncated Cone Protection Structure



3 INDUSTRY OUTLOOK

As large offshore discoveries become _____
economic development of smaller fie _____

potential of the West extension has received continued interest (Husky Energy, 2008).
Expansion plans for both the Terra Nova and Hibernia fields also indicate the trend in
harnessing the full potential of Newfoundland and Labrador's oil and gas resources. The
following figure shows the approximate location of the aforementioned fields with



Figure 6- Offshore Newfoundland and Labrador Oilfields (Rigzone, 2008)

As costs escalate due to strong global demand for services, resources and materials, it is becoming increasingly difficult to make project economics work. The White Rose Southern expansion, for example, adds only a 10% increment to the stated oil reserves but will cost 25 % of the original White Rose development budget (The Canadian Press,

province is expected to reach the 400,000 Barrels per Day (BPD) mark with production

expansion of the industry, larger stand-alone field developments or smaller field developments with tie-back to existing infrastructure is required. Park (2007) discussed production trends for the three current producing fields on the Grand Banks: in 2007, a 30 percent decrease in production was predicted by 2011. Without additional development

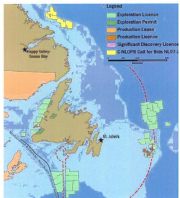
The majority of oil and gas activity has been focused in the Jeanne D'Arc Basin which is only one of four basins on the Grand Banks with the geophysical characteristics of oil-bearing rock. All discoveries on the Grand Banks to date have been in this basin while

There are approximately 4 million hectares under license in the offshore areas of exploration licenses granted for less than a quarter of the total available territory. As a result of three separate bids called by the CNLOPB in 2006, six new exploration licenses have been granted for six parcels comprising a total of 604,647 hectares. Three of these parcels, which make up approximately 13% of the total area, are located in the Jeanne O'Arc Basin while the remaining area is in the Western Newfoundland and Labrador offshore region (Department of Natural Resources, Gov. NL 2008). The number of

c 328 wells had been spudded (spudding is the very start of drilling on a new well).

c Total industry expenditures was approximately \$2 billion (>1.8 billion on

barrels of natural gas liquids had been discovered (Department of Natural



4 SUBSEA PROTECTION

4.1 Conventional Protection

4.1.1 Protection Frames for:

Over-trawlable non-snag-free frames

that there is a large enough risk of accidental loading, then some means of protection must be provided to protect against these loads. Protection frames apply when there is a risk of dropped object impact loads or snag loads (fishing gear, anchors). Work is currently ongoing for the assessment of protection structures to withstand stronger and

requirements for over-trawlable and dropped object protection structures. Maximum load expected from dropped object impacts and fishing gear are stipulated. For all multi- is given as 50 kJ. A maximum load of 1 MN for trawl ground rope snag is given in the progressive collapse limit State (PLS) for a non-over-trawlable non-snag-free structure

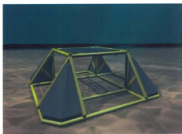


Figure8-GravitySubsea Protection (GSP) Frame (Arup Energy, 2008)

Fail-safe well features play a very important role when evaluating requirements for wellhead protection. Currently, fail-safe systems are adopted as part of the design on every well drilled and perform an important safety function, especially for offshore installations. These safety systems are required to prevent injury to persons, damage to

Subsea completions, which include integral wellhead components, should be designed to

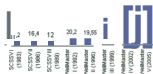
type of fail-safe systems adopted for well installations is the subsea safety valve

emergency such as a wellhead failure. The safety-valve system is designed to be fail-



Perhaps the most regulated component of an oil and gas well, the SCSSV illustrates stringent technical, quality and operational requirements. The industry has made huge reliability. The figure below will illustrate the development in Dappertype downhole safety

Historical TB-SCSSV (Floater) Reliability



by the Foundation for Scientific and Industrial Research at the Norwegian Institute of Technology (SINTEF) and is currently managed by Wellmaster. This study remains the largest yet undertaken into subsurface safety-valve operational experience.

SurCV valves should be installed at sufficient depth in the production string to maintain integrity as they pose a major risk of environmental damage if compromised. Offshore in the tubing string at least 30 m below the casing, as stipulated by the CNOPB under

An analysis performed by Doha (2007) provides insight into the range of depths at which certain downhole components may be set. Significant stresses were found to be nonexistent at typical SCSSV installation levels. Reliance on SCSSV's and other well safety systems offers an obvious solution for reduction in overall risk and up-front

portion of the Xmas tree can be placed under a safety class 2 designation as certain components do not contribute greatly to well integrity. This would effectively reduce the

unprotected well installation would be reduced to approximately 9.7×10^{-5} with active management. These estimates provide motivation for further study of the structural

For an unprotected well, Fowles (2007) estimates an iceberg contact probability of 9.6×10^{-4} . By refining safety class designation of the Christmas tree, approximately 17% of the tree area can be neglected, achieving a collision probability reduction of 17%.

Given iceberg contact has occurred, is approximately 0.097. Integrating this suggestion as well as an SCSSV probability of failure of 0.027 an overall blowout probability of 9.7

51.1 years. Fowles (2007) uses a more conservative value of 36.7, which resulted from

for other potential leak sources. In addition, the dataset may not account for the included

resulting from iceberg contact and the corresponding effect on SCSSV reliability and

To keep reservoir fluids separate from the environment there are series of barriers in a well completion. Primary barriers are in full-time direct contact with hydrocarbons secondary barriers exist as a backup in case of a primary barrier failure and tertiary

Doha (2007) performed a fault tree analysis to roughly predict the overall probability of failure of all well integrity components. Failure of production tubing and annulus

111 bingham and two SCSSV's below. These valves have high reliabilities and their combined efforts give a probability of failure of approximately 8×10^{-7} . The annulus barriers - packers, casing joints, tubing hanger seals, and annular isolation valves - give a much greater overall probability of failure of 0.987. The resulting probability of hydrocarbon release to the environment is approximately 0.0127. This fault tree analysis was performed giving the reliability of all potential leak sources equal weight, when in



Figure 1 | Protective Shelter Concept (Petroleum Directorate Gov. NL 1981)

DORIS Engineering performed a detailed study in 1999 on alternatives to glory holes

protect one to three subsea templates which require a much larger structure than would be required by a single satellite well. Nonetheless, the estimated iceberg loading and necessary structure side slopes would apply. The minimum height was chosen as 10 m

scaled. A horizontal tree, usually around 5 m high would require a structure about 8 m high. Figure 2 illustrates the typical protection structure arrangement. An ice crushing strength of 2 MPa was utilized in determining ice loads which ranged from a resultant of

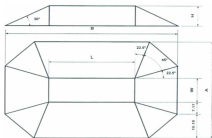


Figure 12- Typical Protection Structure Arrangement (Donis Engineering, 1999)

The following points briefly outline the various structures considered

sloping face design and external shell of concrete or steel. To be floated and

weight version was considered to reduce installation weight. This version would

separately constructed and transported elements. Similar to the monolithic rigid

- Piled segmental rigid structure; this solution was shown to require a large number of piles to resist the lateral loads and therefore was not investigated further

expected leading to the requirement for a considerable amount of additional

An other approach that has been examined is the construction of a protective berm around

practicality of this concept is restricted by the extensive amount of structural material



Bottom scouring icebergs have traversed regions of glory hole installations at depths of up to 1.5 m in the past (Clark, Hetherington, Zavitz, & O'Neil, 1997). The level of uncertainty and prudence for establishing a conservative design basis will respect the safety targets has led recent developments on the Grand Banks, namely White Rose and

Open glory holes originated when drilling activity began in shallow water regions in the incorporated open glory holes providing about 4 m of scour protection (Carick, DeLong,

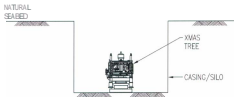
NATURAL (SEABED)



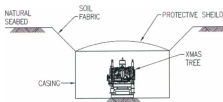
Difficult ground conditions created technical challenges for both the Terra 300 and While Rose glory hole excavations. Cost implications of large open glory holes provide reason for C31 cheaper alternatives. With an estimated cost of \$9.55 MM CDN (2007), glory holes are not a reasonable iceberg contact defense solution for King's Bay.

typically 6 to 10 meters in diameter and up to 20 m depth. Installation would normally be carried out from a drilling rig. The silo is installed prior to commencement of drilling operations. The silo has a weak point at a pre-determined elevation below sea level. In the case of iceberg impact, the silo is sheared at the weak point and the upper part of the silo is sacrificed, leaving the lower part of the silo, the wellhead and the Christmas tree in

A field trial in 1990 to assess the feasibility of using Tornado Drill technology showed



segment by sloped excavated sidewalls. Soil reinforcement fabric may be applied to the sloped excavations if necessary to avoid soil slippage. An inner protective shield could also be incorporated to protect the production equipment from debris and make cleanup



multi-well cluster tie-back developments from a risk and cost perspective. The modified cased hole concept was found to be the most attractive option from a combined cost and

assembly consists of all components essential for maintaining well integrity. The

damage during shear link activation a breakaway flange may be incorporated above the

special running tools and consumable caisson materials are required (Fowles, 2007)

This concept has been implemented on five exploration wells on the Grand Banks by

as production wells if the fields are found to be commercially viable at a later date. As discussed by Fowles, CFER (1988) investigated the collapse behavior of these 1.067 m caisson completions to assess the effectiveness of the intended protection system. While the relatively unsophisticated analysis yielded favorable results, uncertainties in caisson strength and soil parameters were sufficient to suggest that in some situations caisson



Figure 7-Caisson Completion Method (Fowler, 2007)

pipe beneath the ocean floor (Ocean Industry, 1978). The above-mudline height was significantly reduced to 4'6" (approximately 1.5m). Master valves and other critical portions of the system are sunk to a required depth and are designed to automatically shut

not include any critical pressure-containing components and in this particular design is covered by a protective dome. New design features for this concept were prototyped.

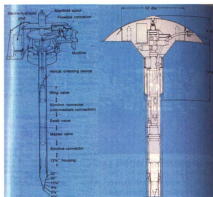
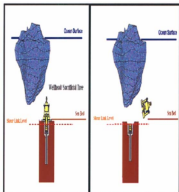


Figure 18-Cameron Iron Works Caisson Completion System ("Ocean Industry, 1978)

The concept proposed by Doha (2007) uses off the shelf components and can be installed using standard procedures; a convenience feature which would increase attractive ICSS of any new concept. The difference between this concept and the caisson completion system is then non-requirement for a lower tree assembly. Instead a single isolation ball valve is installed above the tubing hanger. Between the tubing hanger and weak link in the caisson completion system, there consists a lower and upper tree assembly compared



tubing. The intention of the pipe-in-pipe cross section is to decrease stiffness at the shear

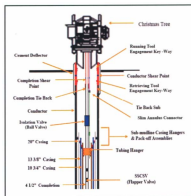


Figure 20 -Arrangement of Shear Link Wellhead System (Doha, 2(07)

of this concept is that no special tool, extra excavation or vessel requirement beyond a drilling rig are required for installation of sub-mudline casing and tubing hangers. All

major factor in the relative economic attractiveness of this concept. A downfall of this concept is that while shear links are intended to relieve horizontal loading, they would

not prevent damage from significant vertical forces. The vertical forces created during the interaction process may compress the shear-link disconnect mechanism inhibiting

operation of well integrity components. In a sample calculation, Doha (2007) assumes

in estimating an overall risk level of 1.27×10^{-6} , which is less than the target safety level of 1×10^{-5} . If we assume ice management is unsuccessful the estimate is increased to

A three year program by GERTH (Groupeement Européen de Recherches Technologiques sur les Hydrocarbures) started in 1976 with the objective of defining and studying a

design of a six-month per-year production scheme as illustrated by Figure 2.1 (see Duval

To place critical components out of range of scouring ice keels it was decided to place the equipment on the bottom of a glory hole. The Xmas tree stood at a height of 4 m with a 5

pull in place to avoid filling by soil cave-ins. Tubing hangers were located in a 1 m caisson approximately 17 m below the excavation bottom. The caisson completion system consisted of a lower tree assembly (slim connector and lower master valve block) and upper tree assembly (upper fail safe master block, weak point, extension, wye diverter, well vertical access system, flow line connection system). The critical pressure-containing components are located below the weak point. The weak point is incorporated in this particular design as a safety measure in the improbable event of an iceberg keel scouring deep enough to impact the subsea structure. The two hydraulically controlled

This concept includes three separate protection schemes in one: open glory hole, cased glory hole, and caisson completion. For application on the Grand Banks or in any other

design concept has had years to develop since this study. The novel llyor operating in

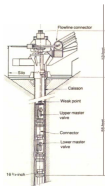


Figure 2-1- Multi-Protection Collar (Duvalet et al., 1980)

development in offshore ice environments. An in depth risk analysis is conducted for each concept as well as a detailed cost analysis. Or several novel concepts presented, only the Xmas MCC with downhole weak shear plane and the modified cased glory hole

options were deemed worthy of further study due to their favorability from commercial.

caisson completion system. A structural based finite element analysis was conducted to predict structural response of a well head to iceberg contact. Optimal levels for key components of the completion are suggested. Results of a risk analysis based on contact frequency and available reliability data show the potential effects of including downhole

As discussed by Doha (2007), it would not be economically feasible for reservoirs less

protection. A recommendation for new subsea protection ideas was put forth

Fowler (2007) performed an in-depth risk and cost study for the various protection concepts. Single well development scenarios as well as multi-well cluster arrangements were analyzed. The annual contact probability was calculated for each concept utilizing

effects of iceberg management with an assumed 85 % effectiveness. From a purely risk based perspective, assuming that ice keel contact results in a well blowout, it was suggested that open glory holes and modified cased glory holes are the most favorable

reduced by shortening the spacing between Xmas trees in the cluster. Fowlow (2007) suggested changing the minimum well spacing from 25 m to 10 m to reduce contact

The cost of developing an oil field is generally higher offshore than on land and than in

cost analysis was undertaken for the aforementioned wellhead protection concepts. The net cost of a particular system is evaluated using the following expression

where C_{net} is the net incremental system cost equal to the incremental CAPEX cost (C_{CAPEX}) plus the cost of risk from icebergs (C_{risk}). Cost of risk can be expressed as

where, P is the annual probability of iceberg contact, R is equipment repair/replace/clean cost, E is environmental and equipment cleanup cost, L_p is cost of loss production, and t

single satellite well development based on net cost. While an unprotected well with and

threshold safety limit of 10^{-5} , based on the assumption that iceberg contact causes a well

comparison of the associated costs for each concept. CAPEX has the greatest influence

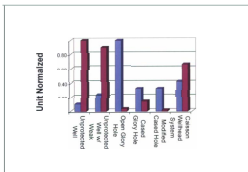


Figure 22- Unit Normalized CAPEX & Cost of Risk (Fowler, 2007)

The majority of icebergs that find their way to the Grand Banks calve off the West

Icebergs travel north in the West Greenland Current, then south in the Baffin and

2003). Figure 230 outlines the general trajectory of icebergs that may drift in the region of



Icebergs may be freely-floating or they may also collide into contact with the seabed causing scours (gouges) or pits. It is worth noting that the Canadian term 'scour' is synonymous with the U.S. term 'gouge'. The number of icebergs which enter the Grand iceberg season extends from March through June. While icebergs are great spectacles for

Acceptable safety or reliability targets associated with subsea installations in ice

onshore codes provide the best design guidance relating to Grand Banks ice issues

	Target Annual	
	Consequences of Failure	Reliability Level
Safety Class 1	Great risk to life or high potential for environmental pollution or damage	1×10^{-5}
Safety Class 2	Small risk to life and low potential for environmental pollution or damage	1×10^{-3}

installation is therefore 1×10^{-5} . Up to about ten entities can be treated individually at this

safety level be maintained at 1×10^{-1} , thereby increasing the safety requirement for each

or injection wells, the environmental impact will be less severe and therefore the safety

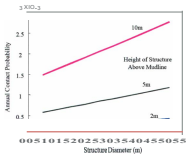
waterline structures be separate from the general sea ice load problem. Iceberg loads for

They showed the effect of lowering the vertical profile height of a subsea installation on

between 10^{-4} and 10^{-3} which is 100 high for a safety class 1 installation even though a full well blowout is not necessarily a result of impact. A main recommendation from this paper was to assess the risk to structures that protrude above the seabed by simulation of

To assess iceberg risk to subsea installations which protrude above the mudline we need

to assess the risk of iceberg subsea structure impact. Figure 24 shows the importance of



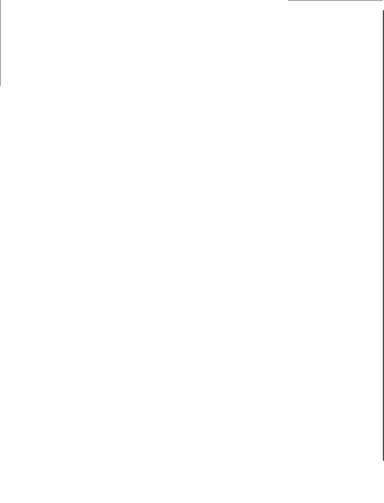
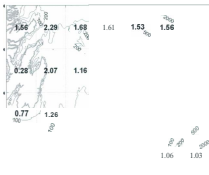


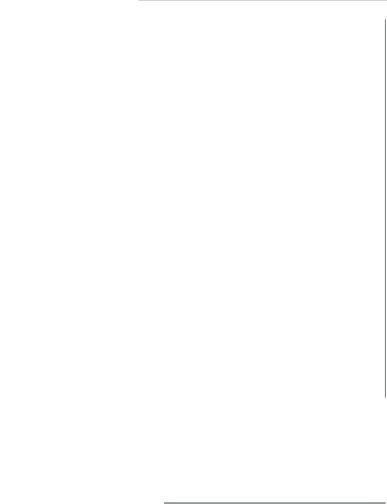
Table 2- Areal Density for Degree Squared Containing Major Developments on the Grand Banks

Time Period	Areal Density (Icebergs/Year/Degree Squared)	Source
1960-2000	0.60	Jordan et al. (1999) in Fowlow (2007)
1981-2000	0.77	Jordan et al. (1999) in Fowlow (2007)
1980-2006	0.79	C-CORE (2007)



In a report by Canine Consultants Ltd. (1999), studies by Brooks (1985), El-Tahan and Davis (1985) and Miller and HCB1 (1985) were discussed. Brooks (1985) showed that an iceberg's waterline length is greater than its draft in about 92 % of the cases analyzed

relationship was satisfied for 197 out of 214 icebergs (approximately 92%). Miller and HCB1 (1985) found iceberg width (maximum dimension measured perpendicular to length axis) was 85 % of the iceberg length. From this result, close correlation between



$$D = L.03 \exp(0.70 + 0.78 \ln(L)) + E_{\epsilon}$$

where ϵ is a normally distributed random variable with a mean of 0 and standard

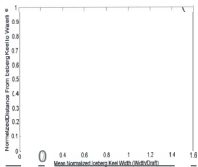
A recent report on ice management (AMEC Earth & Environmental, R.F. McKenna &

Figure 26. Percentage of Free-Floating Keels Capable of Impact (G-CORE, 2007)

An expression relating normalized iceberg width (w^*) to normalized height above the

$$w^* = -9.31z^{0.7} + 5.30z^{0.6} + 0.26$$

known profiles and recommendation is made to incorporate data from many icebergs:



Range	Mean Value
100 m > Draft > 90 m	0.22 m/s
105 m > Draft > 85 m	0.24 m/s
110 m > Draft > 80 m	0.30 m/s
Full Region	0.34 m/s
On-shelf	0.32 m/s
Off-shelf	0.35 m/s

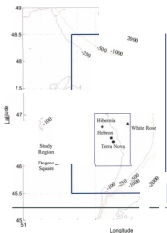
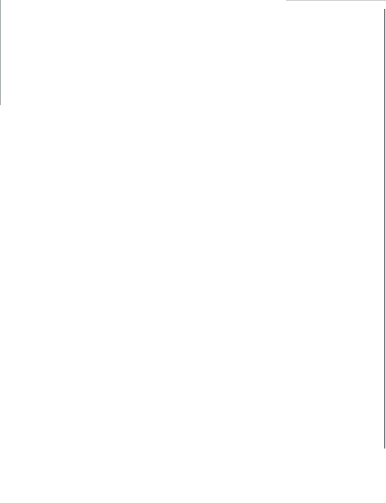


Figure 28-DriftSpeedStudyRegion(Stuckey,2008)

Field specific estimates of mean drift speed should consider the water depth range of the facilities comprising the subsea field layout. It is conservative to use an estimate for the entire study region in the above figure. The following paragraph is a review of other previous estimates of mean drift speed, however, the recent work done by Stuckey (2008)



100,000 km²) include the northeast Grand Banks, Flemish Pass and the western portion

scour density was 0.56 scours/km² and in depths greater than 110 m and density of 0.86 scours/km². The variability in local level scour density is noted; therefore

region and a density of 1.2-1.3 scours/km² between 100-150 m water depth (K.R.

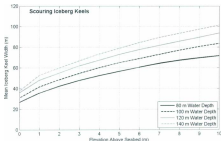
incorporated into the GBSC. A mean scour density of 2.64 scours/km² was determined for the 150 km² region

Geological Inference - Upper Bound		
<u>Geological Inference - Lower Bound</u>	<u>8.3×10^3</u>	

Scour depths are difficult to measure consistently due to information from various

(Myers & Campbell, 1996) are in close agreement; for water depths ranging from 80-120





through an example pertinent to this study. The theory for this approach was first presented by Sanderson (1988), who developed the method to determine the frequency of

methods requiring estimates of iceberg flux. The following formulae are recently used

where η_a is the annual average areal density of icebergs, r'_d is the proportion of icebergs with draft capable of contacting the facility, W_n is the mean width of free-floating iceberg keels at the top of the facility, U is the mean iceberg drift speed, and O_f is

$$\eta_f = 0.032 \times \left(\frac{0.79 \text{ deg}^{-2}}{(\cos(49) \times 1.237 \times 10^3)} \right) \times 10^{-6} \text{ J}_1^{-1} (46.67 + 2.1) \times 0.34^\circ, \times 3.16 \times 10^{-7} \text{ s/yr}$$

$$= 2.26 \times 10^{-7} \text{ yr}^{-1}$$

where p_s is the scour rate, L_j is the mean scour length, W_k is the mean scouring iceberg keel width at the top of the structure, and O_j is the effective structure diameter

$$\eta_s = 7 \times 10^{-4} \text{ km}^{-2} \text{ yr}^{-1} \times 10^{-6} \text{ km}^2/\text{m}^2 (72\text{m} + 21\text{m}) \times 650\text{m}$$

$$= 4.23 \times 10^{-5}$$

$$\begin{aligned}\eta &= \eta_f + \eta_i \\ &= 2.26 \times 10^{-7} + 4.23 \times 10^{-7} \\ &= 2.31 \times 10^{-7}\end{aligned}$$

Return periods for contact with each type of approaching iceberg can be determined by taking the inverse of the contact frequencies. The return period for contact with a freely-floating iceberg is approximately 442 years compared with 23633 years for a scouring iceberg. It is clear that freely-floating icebergs dominate contact risk to a subsea

The additional contact risk from pining icebergs (icebergs that create round or oval scars on the seabed) will be negligible when compared to the risk from freely-floating

Table 5- Input Parameters for Total Contact Probability of a Subsea Facility
Protruding Above the Mudline

	D_f		
Areal Density	η_0	0.79 /degree squared	
The Proportion of Icebergs with Drafts Between d_m and d_m+h	r'_d		
Effective Keel Width (freely-floating icebergs)	\overline{W}_A		SCC Item 5.2.4/Crossdale et al (2000)
Mean Iceberg Drift Speed	\overline{U}		
Annual Scour Rate	ρ_s		
Effective Keel Width (scouring icebergs)	\overline{W}_s		
Mean Scour Length	\overline{L}_s		

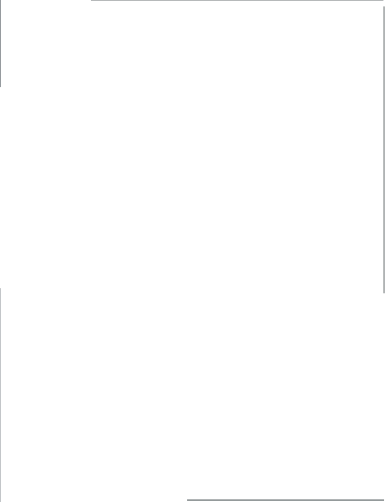
in second place with 5 percent of operations followed by water cannons, ncIS, and two-

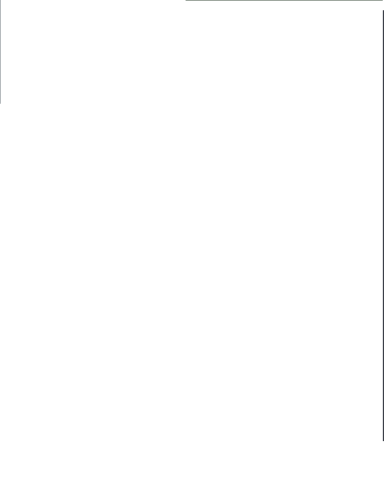
in some early reports, has been dismissed due to the associated dangers (Barron et al.,

The following table gives the results of the analysis based on these two definitions of low

Table 6- Ice Management Operational Success (Barron et al., 2005)

Definition	Number of Operations	Percentage of Total
Operational Success	1492	99.1%
Technical Success	1287	85.5%





provides a good fit to empirical data for areas ranging 0.6 m^2 to 6 m^2 . To determine local ice pressures (I_s) corresponding to an exceedance probability (p_s) the following

$$I_s = \alpha \{-\ln[-\ln(1 - p_s)] + \ln \mu\}$$

where p can be determined with knowledge of mean event duration t and contact

frequency f presents the number of events per unit time. Contact frequency which

(ramming of Kigoriak vessel, mean duration equals 0.7 s). It is assumed here that each contact qualifies as an event for further detail and explanation see (Jordan et al., 1993)

pressure-area relationships for calculation of global ice forces. Global ice crushing pressure can be estimated by the pressure-area relationship

$$P = C_p A^{D_p}$$

where $C_p = 1$ and $D_p = 0.4$ may be taken as mean global values, depending on the application. Jordan discusses how these results were derived from a best fit analysis to ship ram data (Jordan, 2001). Both C_p and D_p can be taken randomly to extend the

range of realistic physical situations. The mean is taken in this study as a means of

Parameter	Mean	Standard Deviation	Distribution
C_p	3	1.5	Lognormal
D_p	-0.4	0.2	Normal

It is recognized that high local pressures may exist on smaller areas. Local pressure

curve in Figure 30. Focusing on the 10,000 year local pressure curve it is evident that local pressures at areas greater than around 13 m^2 actually dip below pressures expected globally. At the point where these curves intersect a transition from local to global

mean global pressure calculated for the incremental area in contact. If for example we assume full envelopment of a single tubular member (with a nominal projected area of approximately 7 m^2) upon initial contact the area is already close to the local to global

this preliminary analysis, the effects of high local pressures over small contact areas will

procedures may best capture this response mechanism and is a recommended course of

Parameter	Value	Preliminary estimate (P. Stuckey, personal communication, July 20, 2008)
η	2.31×10^{-4}	Calculated in Section 5.4

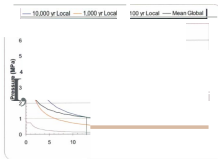


Figure 30- Local Pressure-Area Curves for Varying Return Period & Mean Global Pressure-Area Curve

Iceberg keels scour the seabed when they drift into water depths shallower than their

playback cycle in the model, which balanced seabed reaction forces, environmental

iceberg hydrostatics is a sensitive parameter in modeling the scour process. Limited

hydrostatics and consequently leads to significant differences in modeled scour lengths

and scouring icebergs were considered. Based on the contact area, a force was calculated from the sampled pressure. Contact areas resulting from free-healing and scouring icebergs were considered in the analysis. Pressure was assumed to develop uniformly over the entire rigid-body contact area and all impacts were assumed to be direct hits

with drafts capable of impacting a structure well 5.5 m in height will pitch sufficiently to allow the keel to pass over the IOP of the structure. For the remainder of the iceberg population, the distance required to dissipate the kinetic energy of the iceberg was calculated based on initial iceberg drift velocity, iceberg mass and impact force applied at

Iceberg type	Force (MN)	Moment (MN·m)		
	Mean	Std.	Mean	Std.
Free-floating	3.3	4.3	9.2	6.6
Scourin	11.9	8.2	18.7	10.3

exceeding 2.8 m^2 10aStima ice keel forces on alternative protection structures for the

loads ranged from a resultant 140 MN-200 MN on structures which varied greatly in

icebergs with subsurface would be in the order of 10-30 MN with significant downward

icebergs. These significant downward forces may have been a result of conservatism in

estimating ice crushing pressures. The coefficient C_1 is taken as 7 and the exponent n is 1.0,

sacrificial well equipment be located above the seabed and critical equipment be installed



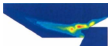
Figure 31-Geometry of Truncated Cone (North Atlantic Offshore Engineering Alliance).

As part of the study, the determination of iceberg loads by energy conservation and momentum conservation approaches was investigated. As well, an numerical model of iceberg motion was accomplished using the discrete element computer package known as

A recent study by Gudmestad and Lifero (2007) assessed ice loads of an ice-ridge keel on arigid subsea structure. Two simplified 2D numerical models were developed to

cohesion, keel angle of internal friction). The analysis was performed for shallow, intended ice water depths in ice covered waters. A sample output graph showed annual exceedance probability versus contact force per meter (width) for a 10m wide structure extending 5m above the mudline in 30 m water depth. It was determined that keel depth or contact height, has greatest sensitivity. Possible interaction scenarios were developed

Confined keels, with the high driving forces of the surrounding ice floes were presumed to either shear at the keel, or fail locally and/or globally. Results of the analysis showed that in all but two cases, local propagating failure was the mechanism that limited the keel



The energy approach described herein follows the same procedure outlined in the 1996

relationships had to be modified accordingly: explanation is given throughout this

ice loads imparted on a subsea structure can be illustrated using an application of the work-energy principle. Upon impact, the initial kinetic energy of the iceberg will be dissipated through crushing of the ice keel (indentation energy), rotation and heave of the iceberg, and strain energy dissipated by the major load carrying components of the

Energy (2000). The application of the energy approach in this study does not account for

where KE_{init} is the initial kinetic energy of the iceberg, E_c is the energy absorbed in sliding (or crushing), E_i the energy in lifting the iceberg, and E_f in rotating the iceberg

where m is mass, c_a is an added mass coefficient and V is the undisturbed drift speed of the

water surrounding the iceberg. The added mass coefficient can vary between 0.05 for a

extremely high normal forces are generated on contact. Normal and frictional forces can

The moment generated due to the forces at the keel can be calculated by multiplying each force component by its perpendicular distance to the center of gravity of the iceberg.

From the center of gravity of the iceberg, e_x and e_z are the horizontal and vertical

be equal to the righting moment to determine the amount of induced rotation. Righting

stability. It is therefore important to integrate stability calculations when considering the

$$M_{\text{righting}} = \overline{GM} \sin \theta \cdot \Delta$$

where \overline{GM} is the distance from the center of gravity to the metacenter height and Δ is

where ∇ is the submerged or displaced volume. The distance \overline{GM} is given by

where \overline{KB} is the distance from the keel to center of buoyancy, \overline{BM} is the distance from the center of buoyancy to the metacenter, and \overline{KG} is the distance from the keel to

$$M_{\text{righting}} = (\overline{KB} + \overline{BM} - \overline{KG}) \sin \theta \cdot \Delta$$

where I_{xx} is the moment of inertia of the waterplane area, and ∇ is the submerged or displaced volume. Equation 6-15 can then be rearranged as follows

$$\Rightarrow M_{\text{righting}} = \overline{BM} \sin \theta \cdot \Delta - (\overline{KG} - \overline{KB}) \sin \theta \cdot \Delta$$

$$\Rightarrow M_{\text{righting}} = \frac{I_{xx}}{\nabla} \sin \theta \cdot \Delta - \overline{BG} \sin \theta \cdot \Delta$$

$$\Rightarrow M_{\text{righting}} = \left(\frac{I_{xx}}{\nabla} \Delta - \overline{BG} \Delta \right) \sin \theta$$

$$\Rightarrow M_{\text{righting}} = (J_{wp} \rho_w g - \overline{BG} \Delta) \sin \theta$$

If we assume that for small angles, $\sin \theta \approx \theta$, the expression can be further simplified

and isberg some angle without performing detailed stability calculations. For an initial

calculate the necessary applied moment at the keel to rotate the ice
 estimate of the waterplane moment of inertia. Energy dissipated th
 calculated by:

$$E = \frac{1}{2} I_{wp} \omega^2$$

shaped iceberg will be examined. The key parameters from a hydrostatic analysis will be related upon initial contact, lessening the amount of energy to be dissipated through crushing of the keel. Energy stored in heave displacement will in turn add energy to the system in the form of potential energy: the net balance will likely be negligible towards the dissipation of energy. The following paragraph provides the procedure for

Assuming basic keel width, side-slope angle (α) and height (h) allows for calculation of the radius of the top area of the truncated cone (refer to Figure 33). With the geometry established, hydrostatics can be used for several key parameters required to determine the stability of the assumed iceberg shape. To obtain the desired draft, the height can be adjusted and the hydrostatics performed iteratively: the following describes this process

After selecting a base radius, side-slope angle and height, the top radius can be calculated by simple trigonometry. The volume of the truncated cone (in this case, the volume of ice)

where h , r_b and r_t are illustrated in Figure 33. The weight of the ice (W_{ice}) which is equal to the buoyant force (FB), can then be calculated by multiplying the volume of ice by the unit weight, assuming the density of ice is approximately 925 kg/m^3

density of seawater is 1025 kg/m^3

$$V_{\text{water_displaced}} = \frac{W}{\rho_w g} \quad (\text{Eq. 6-25})$$

required; a solution can be achieved iteratively or using a solver tool such as goal seek in excel. Furthermore, changes to the geometry (i.e. overall height) can be made to achieve the desired draft

important index of stability at small angles of rotation. Since we are dealing with symmetric geometry in this example, there is no need to distinguish between longitudinal

can be calculated by equation 6-14. The location of the center of gravity for a truncated

$$G = h - \frac{\left[\frac{h(r_1^2 + 2r_1r_2 + 3r_2^2)}{2(r_1^2 + r_1r_2 + r_2^2)} \right]}{}$$

calculated using equation 6-16, where A_0 for a circular waterplane cross sectional area is

After calculating these key parameters, it is relatively simple to calculate the stability curve (\overline{GZ} curve) for the given shape, taking advantage of the small angle approximation. With sufficient accuracy for all practical purposes the distance GZ can

for a given angle of rotation. Knowing these parameters related to ice-berg stability

geometry and rotation of the ice-berg are not accounted for. The normal contact area is

pressure can be approximated by the nominal pressure-area relationship giving normal

will be a sharp increase, and the accumulation of area will continue on linearly thereafter

angle of the structure and the coefficient of friction between the keel and structure face

Figure 34 illustrates the growth of the contact area with horizontal penetration as well as

the normal and component forces. The applied moment at the keel is then calculated

enabling resolution of the rotation angle. We can also solve for the vertical uplift as the

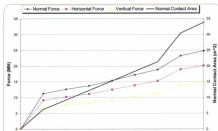
displacements, the work done by surge, heave and pitch motions can be determined by

integration. The cumulative sum of energies after each increment is compared to the

sample calculation is performed for a truncated cone shaped rectangular frame structure as summarized by the parameters

Table 10- Sample Calculation Parameters Tranca

[illegible]



of energies from each contributing mechanism with incremental penetration until all of the energy has been dissipated, as indicated by the % Total Work Done line. From this figure we can see that crushing energy increases rapidly at first due to the fact that the

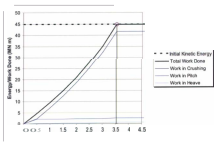


Figure 35. Work Done versus Penetration- Truncated Cone Iceberg Geometry

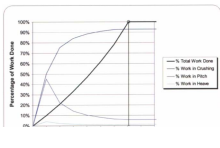


Figure 36- % Work Done versus Penetration-Truncated Cone Iceberg Geometry

To establish an upper and lower estimate of initial stability, and conversely a lower bound estimate of the energy dissipated through rotation, we can simulate a rectangular prism shape. This presumption is based on the idea that the balance of moments about the center of gravity will be zero as the horizontal and vertical forces applied at the keel and the moment arms will be practically the same. The calculation procedure is the same as for the previous example, aside from the difference in geometry. The following table

[illegible]

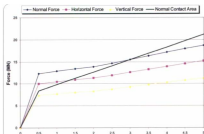


Figure 37. Contact Area & Force versus Penetration-Tabular Iceberg Geometry

As can be seen in Figure 39, nearly all of the work is done by crushing of the keel. The

stability in comparison to the previous shape. The other factor which contributes greatly

centerline of the iceberg. The applied moment at the keel about the center of rotation is equal to the horizontal force at the keel multiplied by the distance from the point of

horizontal distance is only a small amount less than the vertical distance, therefore the applied moment at the keel is much lower than for the previous case. From the results presented in the following two figures, it is clear that the majority of energy is dissipated through crushing before the iceberg comes to rest after surging almost 500

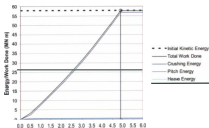


Figure 35- Work Done versus Penetration for Tabular Iceberg Geometry

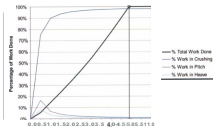


Figure 39- % Work Done versus Penetration - Tabular Iceberg Geometry

The parallel axis theorem for composite sections is used to find G and B . An elliptical

The submerged volume and waterplane moment of inertia are calculated to determine the

than the proportion from pitching. This is likely due to the difference in the slope of the

theoretically came to rest it had pitched about just greater than 0.23° which closely agrees with a mean pitch of 0.24° presented in a similar model used to predict iceberg dynamic

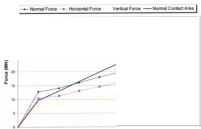


Figure 41-Contact Area & Force versus Penetration - Mean Iceberg Geometry

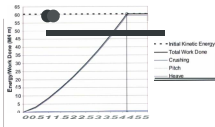


Figure 42- Work Done versus Penetration - Mean Iceberg Geometry

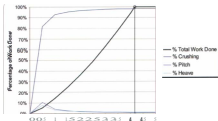
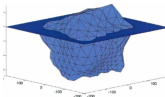


Figure 43- % Work Done versus Penetration - Mean Iceberg Geometry

displaced entirely through crushing of the keel may be conservative in cases where the initial point of contact is far from the center of rotation of the iceberg. The recommended course of action is to scale existing iceberg profiles of icebergs such that they will have sufficient draft to impact a substructure of a given height in a given water depth. For each iceberg, the stability about the varying directions should be determined. Representative contact geometry can be assumed to produce a contact area-penetration

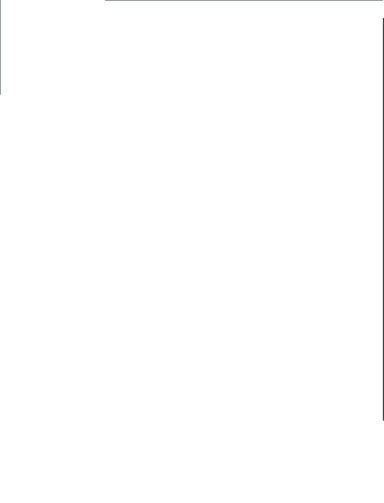
The iceberg in Figure 44 for example will behave differently based on the point of contact. The metacentric height will change about different axes as well as the distance

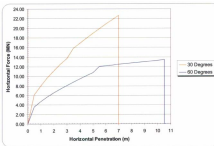
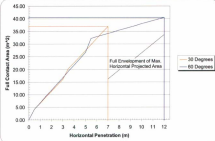
produce very different results with change in the orientation of impact. Application of the Monte Carlo approach is recommended to cover a wide range of iceberg profiles. With



are made to simplify the load transfer process. Scenarios are developed to assess the structural response of a protection frame to loads representative of those that would be imposed during contact with an ice keel. Although a wide range of iceberg load events is

the ice-structure interaction process for contact with seabed installations. Based on this assumption, horizontal forces generated by ice crushing pressures and surge penetration will be used conservatively to calculate total work done. Since heave and pitch motions





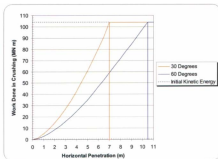
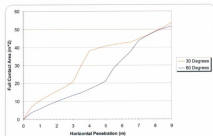
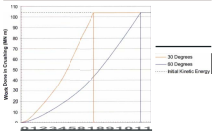
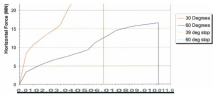
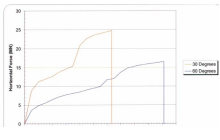


Figure 47- Work Done in Crushing versus Penetration (Rectangular Frame Structure)

6.4.2 Contact with Truncated Cone Protection Structure







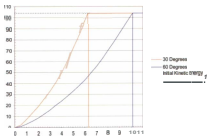


Figure53- Work Done in Crushing versus Penetration (Truncated Dome Structure)

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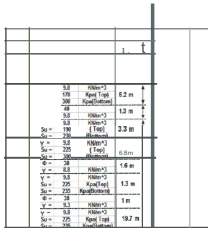
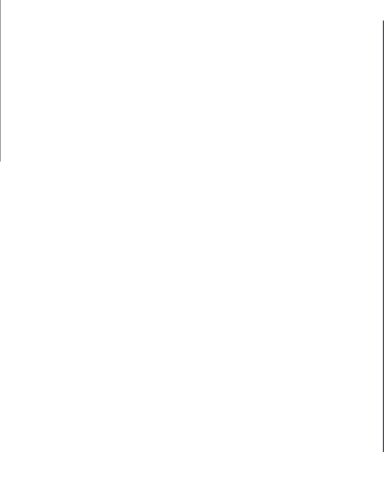


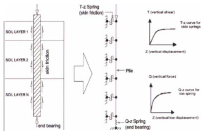
Figure 54-Soil Strength Profile NW Anchor Pile White Rose Field (Doha, 2007)

Each pile connected to the structure is modeled as a separate entity based on the assumption that single-pile load and deflection characteristics will not be affected by adjacent piles. Generally, for pile spacing greater than eight diameters, pile group effects may not have to be evaluated (A.P. L. 2000). Empirical methods, based on model and





- 0.5 m depth
- 1.0 m depth
- 1.5 m depth
- 2.0 m depth
- 2.5 m depth
- 3.0 m depth
- 3.5 m depth
- 4.0 m depth
- 4.5 m depth
- 5.0 m depth



where N_q and N_r are bearing capacity factors for vertical strip footings, loaded vertically in the downward direction. γ is the effective soil unit weight. λ is the total soil

$$q_p = cN_c D$$

a relative displacement of approximately $\Delta_{\phi'} = 0.1D$ for granular soils and $\Delta_{\phi'} = 0.2D$

$$N_c = \frac{[\cot(\phi + 0.001)] \left\{ \exp[\pi \tan(\phi + 0.001)] \tan^2 \left(45 + \frac{\phi + 0.001}{2} \right) - 1 \right\}}{2}$$

$$N_q = \exp(\pi \tan \phi) \tan^2 \left(45 + \frac{\phi}{2} \right)$$

$$N_r = e^{(6.09\phi - 2.5)}$$

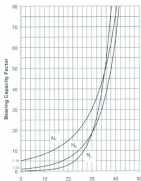
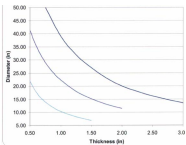


Figure 57- Plotted Values of Vertical Bearing Capacity Factors (American Lifelines Alliance, 2001)

distance $\leq 6\psi$ and remains constant thereafter. In the present study it is assumed that the

$$M_{\text{applied_max}} = \text{Max} \left\{ \frac{w}{12} \left(6Lx - L^2 - 6x^2 \right) \right\}$$

$$M_p = \left(0.05 - 0.0015 \frac{D}{t} \right) \cdot SMYS \cdot D^2 \cdot L$$



Load-displacement relationships for tubular members of offshore structures impacted by tool joints on subsea tubular-frame protection structures the same formula can be applied. By applying forces resulting from pressures representative of ice crushing strength, we can approximately determine required member sizes to prevent excessive plastic indentation

where F is the force and δ_0 represents the elastic displacement, E is Young's Modulus, r

length of the contact area along the direction of the tube. The characteristic length is a

discussed by Bai (2003), an empirical equation was obtained through the analysis of linear finite shell element analysis results and indentation tests. A mean value is found to

$$F_0 = 2\sigma_s T^2 L_C / D$$

indentation δ_p can be calculated using a semi-empirical equation. Through energy

unloading point. The local displacement at the load point will be for a load larger than Poisson's

As a simple calculation, scicli a tubular member with a diameter of 0.9m, and thickness

Applying an effective area of _____

relationship gives $P = 3 \times 1.54$ _____

gives a force, $F = 2.34 \text{ MPa} \times l$ _____

elastic and plastic displacements are, $\epsilon_e = 18.36 \text{ mm}$ and $\epsilon_p = 24.62 \text{ mm}$. ASSIlinga

predict the hardening behavior in the plastic region of the Stress-strain curve (Wikipedia

grades(Walker&Williams, 1995). Figure 59 shows a sample stress-strain curve for x-

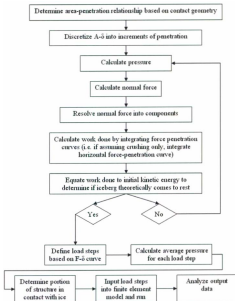
		2.55	12.03
		2.23	13.67
(-52			17.99
(-56		1.66	
(-60		1.48	18.99
(-65			25.58
(-70		1.13	27.43
		0.86	37.00



modeled using the same elements as for pipes (B31). Pipe sections are defined for the

pile and structural member response is based on Timoshenko beam theory assuming
 defined by nonlinear spring elements in two transverse directions and the longitudinal
 on input parameters (structural dimensions, tubular member size, pile depth and size, and
 protection structure) is then created and tied to the pile foundation. The load application is
 approach previously described. The loads are entered into an automated input file
 generator which creates the input file to be evaluated by ABAQUS/Standard with
 and verification through simple structural models. It is recognized that stress intensity
 analysis and calibration of the finite element model is recommended

The following Orzechan outlines the overall analysis procedure. The main idea is that



This section presents the results of the finite element analyses described in the preceding chapter. The results are first illustrated for the rectangular frame model. The effect of incorporating curved versus straight members is then shown through comparison of the structural response of the truncated cone and dome models. Based on the outcome of

Note that the figures provided are scaled to improve visibility of the deformation trends;

undeformed geometries are provided in Section 5. Contact areas are highlighted and

Table 4- Input Parameters for Rectangular Frame Global Structural Response Analysis

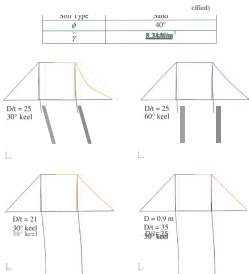


Figure 60- Global Structural Response of Rectangular Frame Protection Structure (2.5x magnification)

Pile Thickness	0.050 m
Tubular Diameter	0.6 m (unless otherwise specified)
Soil Type	Sand
ϕ	40°
γ	8.3 kN/m ³

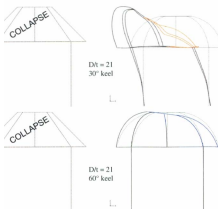
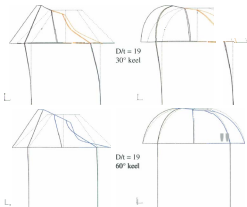


Figure 6-1-Comparison of Truncated Cone and DOME Structures (2.5x)



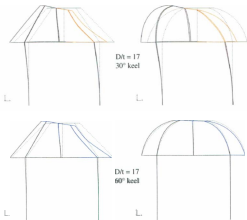


Figure 63-Comparison of Truncated Cone and Dome Structures(2.5x)- Continued

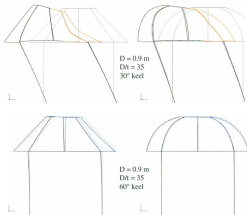


Figure 64-Comparison of Truncated Cone and Dome StrucUrcs (2.5x)-C-continued

configurations providing increased vertical support for the circular base models could

requirement for the truncated cone and dome geometries. The rectangular configuration

the circular base, adjacent members under direct pressure, for the other shapes. Since

the side of impact have displaced inwards about 0.9 m. The interaction with the 30° keel

greater vertical component resulting in less horizontal displacement than its counterpart

Focusing on the frame response with $D/I = 2.5$ in Figure 60, the point of first yield of the

Figure 65. The area between two consecutive vertical lines represents a load slip. At this point the ice keel has surged about 3 meters and about 27 % of the assumed initial

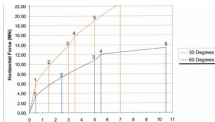


Figure 65- Horizontal Force-Penetration Curve - Load Slip Segments

In a side-by-side comparison of the truncated cone and dome models the results shown in Figure 61-Figure 64 consistently demonstrate the improved effectiveness of the dome-like structure in controlling high vertical loads imposed by the 600 keel. Comparison of

Figure 64. The added stiffness sends the forces through the path of least resistance to the

To improve the performance of the truncated cone or dome models it is recommended to

they would likely be more competent in the case of a center-to-center wheel contact

rectangular frame configuration increases its attractiveness. The inclined sections
extending from each side of the interior frame could potentially be constructed and

create unique and extreme challenges in every aspect of new developments large and

A potential solution for the protection of single satellite wells was presented. Three separate configurations were considered under the category of a tubular frame protection

The energy approach was employed with consideration of iceberg stability for simple shapes to assess global loading. The initial kinetic energy of sample icebergs was equated to the work done in crushing failure of the ice keel over the contact area, and the

simplification of the energy approach which conservatively assumed crushing failure exclusively - in lieu of better understanding - was used to predictic loads which were predicted for each structural configuration and a discussion of the results ensued

The rectangular frame configuration behaved well under the predicted global loads. The high venical pressures without increasing the member size relative to the rectangular frame model: venical stiffening was recommended. In comparing the braced cone and

here required all the area-penetration relationship as a function of the keel shape of each discretely simulated profile. Direct central interaction events with icebergs traveling horizontally have been assumed in the current study. It is recommended to extend loading scenarios to incorporate non-central contact which would induce rotation about the vertical axis. The potential for vertical impact from an iceberg with significant heave

A potential avenue to capture varying stability and keel geometry is to employ distribution of iceberg metacentric height (with associated mass and velocity terms) and keel angle. With keel angle, the area-penetration relationship can be estimated based on contact with known structure geometry. From the area-penetration curve, the crushing pressure can be calculated from which the normal force can be calculated and resolved accordingly. The applied horizontal and vertical forces at the keel determine how much the iceberg will pitch and heave depending on the stability of the iceberg, which is represented by its metacentric height. A more accurate description of the load path during the ice-structure interaction can be achieved by updating the position of the keel with respect to the structure at each increment of horizontal penetration.

take advantage of the Coupled Lagrangian Eulerian approach being developed in ABAQUS, although the constitutive models for ice would be a significant challenge.

Further work on defining keel geometry is recommended to assess the general potential for keel protrusions to induce local member failure. In addition to this, the effects of local ice pressures on tubular members should be assessed to further understand potential

Since pile installation on the Grand Banks may be difficult, it may prove beneficial to consider an alternative means to establish adequate lateral resistance. The main downfall

vessel support) and logistics optimization is needed. Once the structural frame

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pile thickness was not specified in the available literature, so a D/b ratio of 25 was

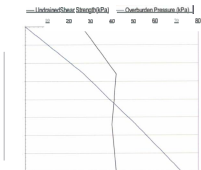


Figure 66-Assumed Undrained Shear Strength Profile (Karlsrud et al., 1993)

is approximately 25 %. A comparison of bending moment response for a 20 kN load also

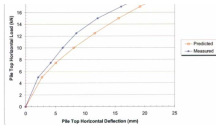


Figure 67- Horizontal Load versus Lateral Displacement in Clay

Figure 68-Depth versus Bending Moment Single Pile in Clay

In a study which examined science and empiricism in foundation design, analytical

2003). As discussed by Randolph, the method of Jardine and Chow, known as the MTD

diameter pile of 50 mm wall thickness. The pile embedment depth was taken as 10 m.

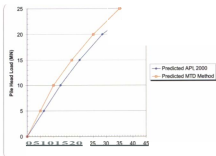
in clay soil with properties similar to those found offshore West Africa. The effective

unit weight was taken as 3.5 kN/m³ and undrained shear strength (s_u) is approximated



Figure 69-Undrained Shear Strength and Shaft Friction versus Depth in Clay

displacement obtained from the MTD method and the API guidelines are compared in



embedded to a depth of approximately 22 m in sand with an internal angle of friction of 39° and an effective unit weight of 10.4 kN/m^3 . The water table was maintained above the ground surface during loading to simulate conditions which would exist at an offshore

pile, beginning with a load of small magnitude. Groundline displacement and bending

parameters of the field test were matched in the numerical analysis. Results showed good agreement between measured and predicted groundline deflections (see Figure 71) with an average error of approximately 16.5 %. A bending moment curve was given in the report for a 266 kN lateral load. Figure 72 displays a comparison of the calculated and measured bending moment curve for the 266 kN load. Excellent agreement is achieved

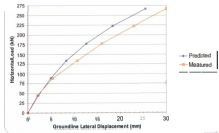
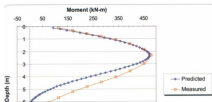


Figure 71- Horizontal Load versus Lateral Displacement in Sand



A 1994 study by Al-Shafieial, involved testing and analysis of tension and compression loads on 0.6 m diameter steel piles driven to 18 m depth in sand. Figure 73 shows a comparison between the idealized bilinear t-z curve approximated using the API guidelines and the measured t-z curve from the physical test at 2 m depth.

